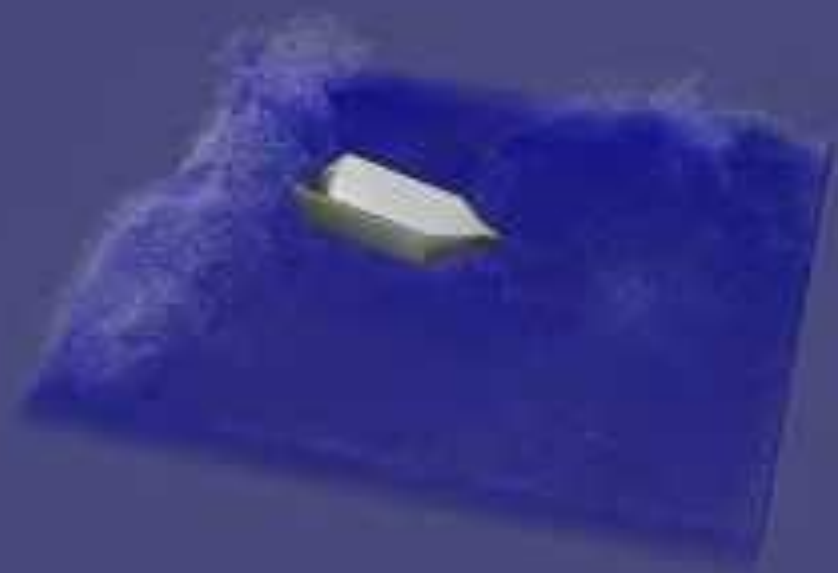


Project: Waterboat

Group: PhysIT

Phillip Løjmand, Daniil Emtsev, Anton
Maksimov



Physics

1. Explicit WCSPH solver with boundary handling [1]

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2. Two-way rigid body-water coupling [2]

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Friction $F_{i \leftarrow j}^v = -m_i m_j \nu \left(\frac{\max(v_{ij} x_{ij}, 0)}{|x_{ij}|^2 + \epsilon h^2} \right) \nabla W_{ij}$

[1] PBS lecture on SPH + Eurographics Tutorial 2019, section “Boundary handling”

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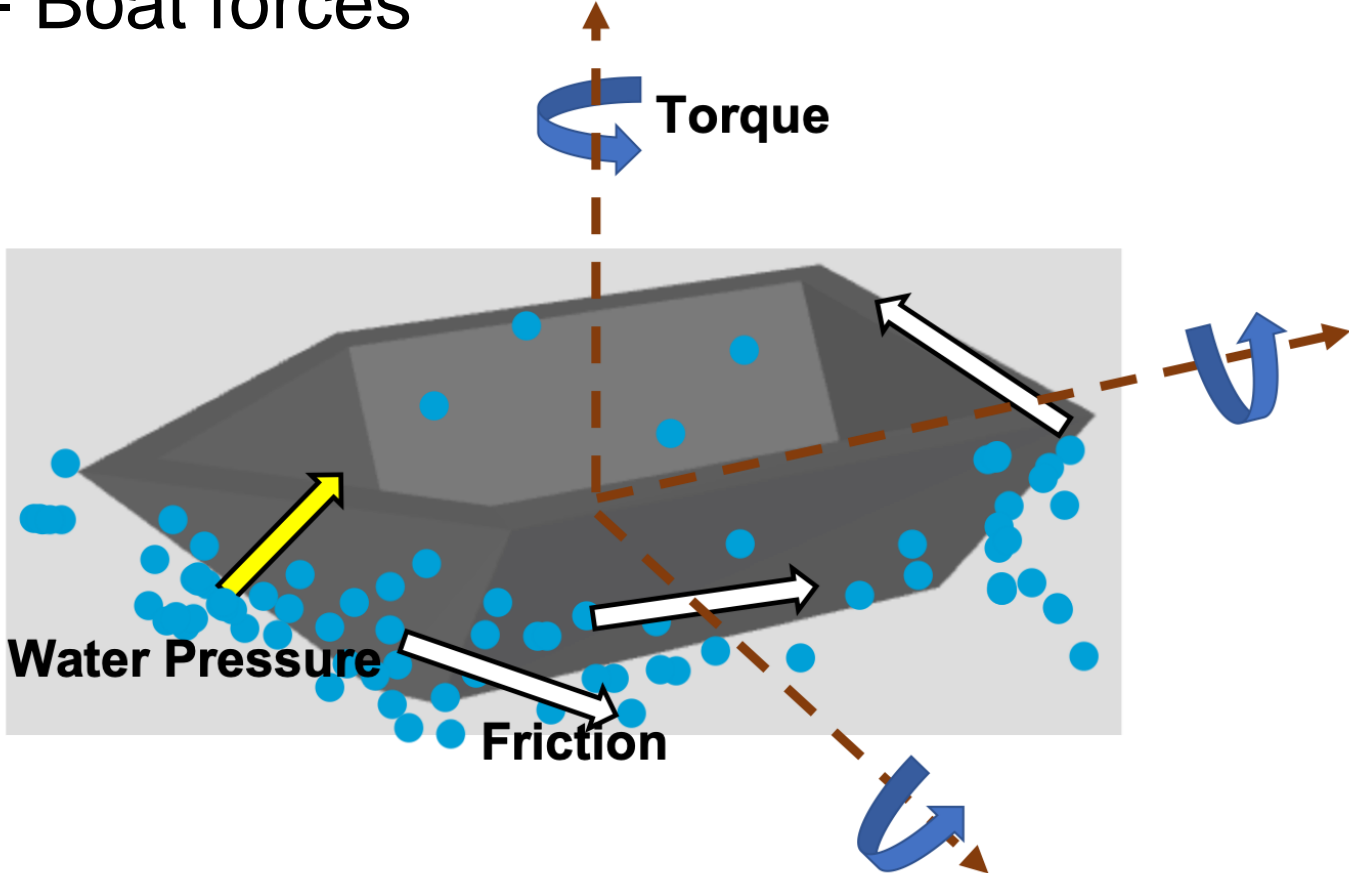
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3. Rigid body movement with boundary repulsion
4. *Parameters tuning*

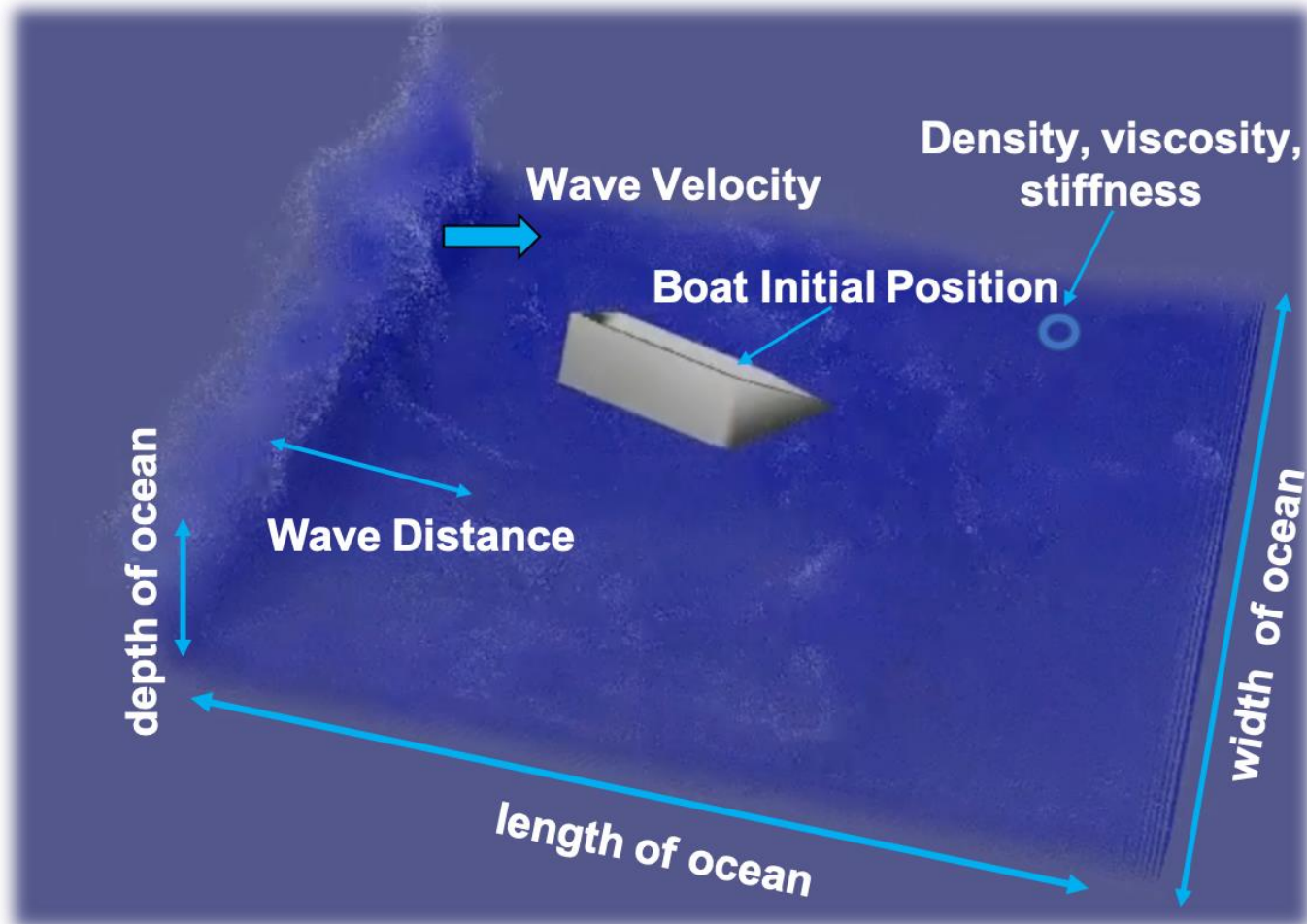
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Water - Boat forces



Interactive parameters



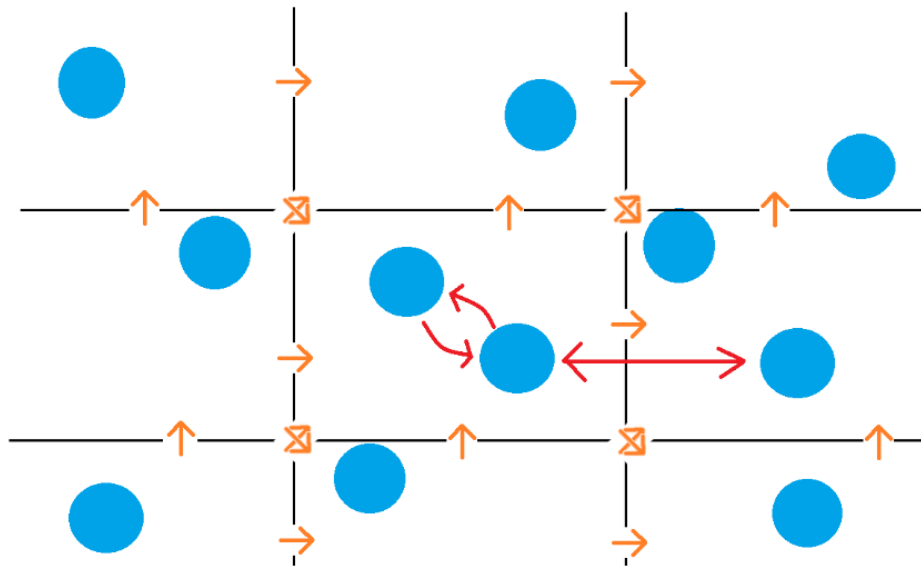
Optimizations

- **Cache locality (~2x)**
 - Grid contains vector of particles and list of pointers to Neighbor-grids lists
 - Particle struct fit in cache-line. Using floats instead of doubles.
 - Bottleneck is particle interactions, not re-arrangements.

	Time (ms)
An iteration of ~1.1M particles	
Reset densities and forces	27.803
Sum densities	(34.5%) 306.700
Update pressures	15.378
Sum forces	(48.3%) 429.419
Update velocities and positions	38.583
Re-arrange particles	(8%) 71.722
Total	889.605

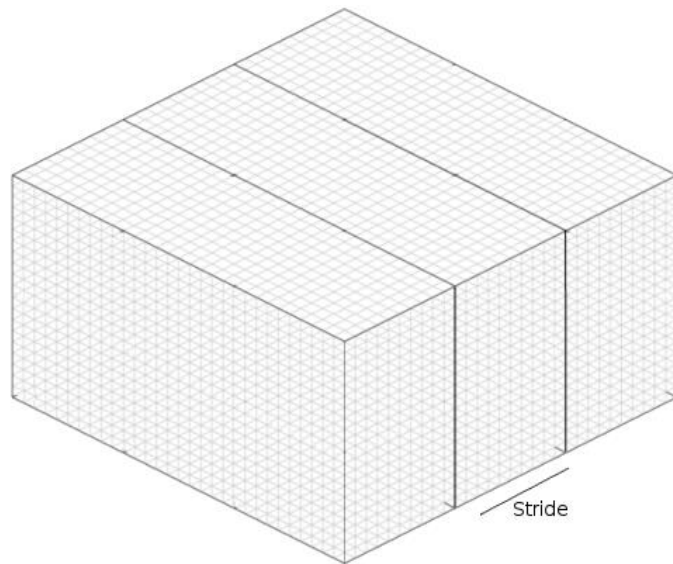
Optimizations

- Cache locality
 - Grid contains vector of particles and list of pointers to Neighbor-grids lists
 - Particle struct fit in cache-line. Using floats instead of doubles.
 - Bottleneck is particle interactions, not re-arrangements.
- **Double update (~1.5x)**
 - **Filters neighbor search**



Optimizations

- Cache locality
 - Grid contains vector of particles and list of pointers to Neighbor-grids lists
 - Particle struct fit in cache-line. Using floats instead of doubles.
 - Bottleneck is particle interactions, not re-arrangements.
- Double update
 - Filters neighbor search
- **Parallelization (2 cores 4 threads, ~2x)**
 - **OpenMp**
 - **Reduced cache coherence overhead by strides**



Optimizations

- Cache locality

- Grid contains vector of particles and list of pointers to Neighbor-grids lists
- Particle struct fit in cache-line. Using floats instead of doubles.
- Bottleneck is particle interactions, not re-arrangements.

- Double update

- Filters neighbor search

- Parallelization

- OpenMp
- Reduced cache coherence overhead by strides

- **Low - level optimizations (~2x)**

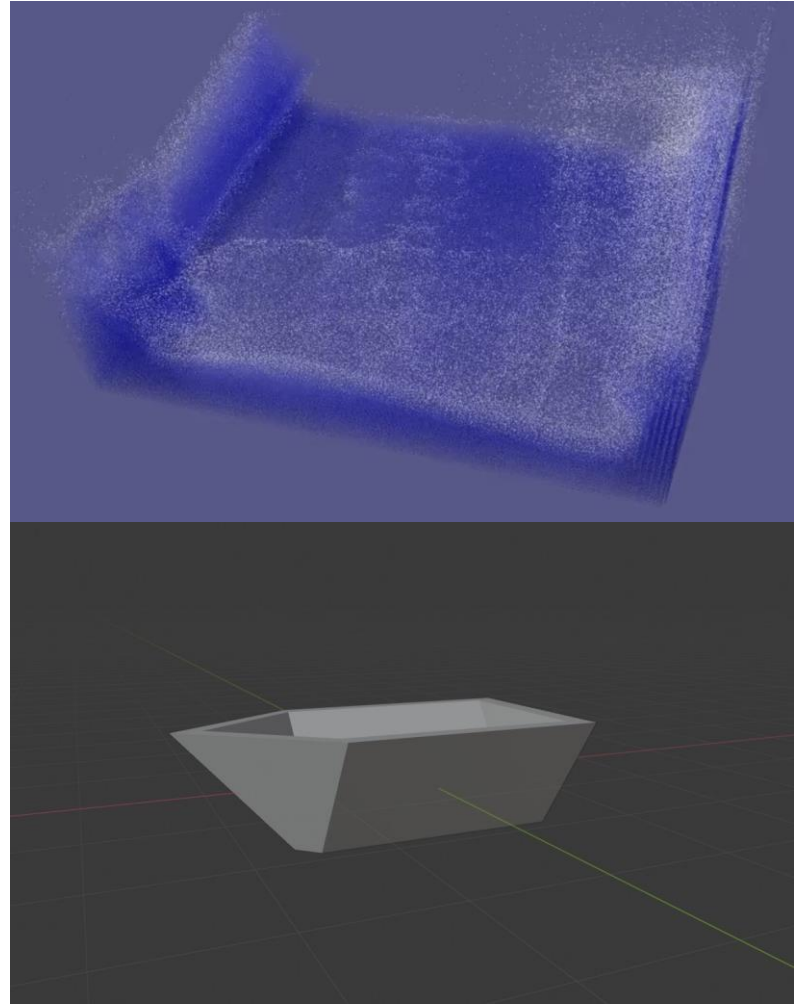
- **Avoid pow and sqrt**
- **Reuse part of calculations in temp variables**

```
inline float fastsqrt(float val) {  
    int tmp = *(int *)&val;  
    tmp -= 1 << 23;  
    tmp = tmp >> 1;  
    tmp += 1 << 29;  
    return *(float *)&tmp;  
}
```

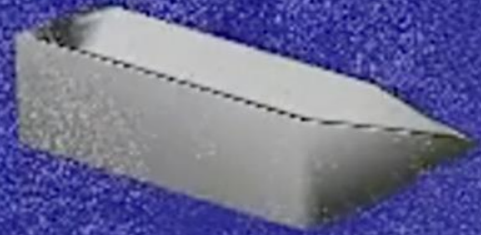
```
d = ParticleDistSQ(p, p2);  
if (d < hsq) {  
    d = fastsqrt(d);  
  
    a = (h - d);  
    a = a * a * a * kernelFactor;  
  
    p.density += m_mass * a;  
  
    if (j != i) {  
        p2.density += m_mass * a;  
    }  
}
```

Visualization

- Dot position/color matrices
- Color based on density - foam imitation
- OpenGL dot transparency
- Blender used to make boat .obj file
- Render to bitmap @ 30fps
- FFmpeg converts bitmap to video



Questions



Parameters

1. Spiky kernel

$$W_{spiky}(r, h) = \frac{15}{\pi h^6} \begin{cases} (h - r)^3, & \text{if } 0 \leq r \leq h \\ 0, & \text{otherwise} \end{cases}$$

1. Pressure

$$p_i = k \left(\left(\frac{\rho_i}{\rho_0} \right)^7 - 1 \right) \quad k = 1000$$

1. Viscosity

$$\nu = 0.5$$